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1  # =====
2  # FILE: DnB_Signal.pm                                     7/05/2020
3  #
4  # SERVICES:  DnB SIGNAL FUNCTIONS
5  #
6  # DESCRIPTION:
7  #   This perl module provides signal related functions used by the DnB model
8  #   railroad control program.
9  #
10 # PERL VERSION: 5.24.1
11 #
12 # =====
13 use strict;
14 # -----
15 # Package Declaration
16 # -----
17 package DnB_Signal;
18 require Exporter;
19 our @ISA = qw(Exporter);
20
21 our @EXPORT = qw(
22     Init_SignalDriver
23     SetSignalColor
24     SetSemaphoreSignal
25     SignalChildProcess
26     TestSignals
27 );
28
29 use DnB_Turnout;
30 use DnB_Message;
31 use Forks::Super;
32 use Time::HiRes qw(sleep);
33
34 # =====
35 # FUNCTION:  Init_SignalDriver
36 #
37 # DESCRIPTION:
38 #   This routine initializes the GPIO pins associated with the LED driver on
39 #   the DnB model railroad. A shift register utilizing multiple 74HC595 chips
40 #   is used. Data is shifted in serially using GPIO pins connected to the data
41 #   and clock inputs of the shift register.
42 #
43 #   A second group of GPIOs is used to control the track power polarity relays.
44 #
45 # CALLING SYNTAX:
46 #   $result = &Init_SignalDriver(\%GpioData, $RegisterLength);
47 #
48 # ARGUMENTS:
49 #   $GpioData          Pointer to GPIO data.
50 #   $RegisterLength    Shift register bit length.
51 #
52 # RETURNED VALUES:
53 #   0 = Success,  1 = Error.
54 #
55 # ACCESSED GLOBAL VARIABLES:
56 #   None.
57 # =====
58 sub Init_SignalDriver {
59     my($GpioData, $RegisterLength) = @_;
60     my($x, $pin);

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61     &DisplayDebug(2, "Init_SignalDriver, RegisterLength: $RegisterLength");
62
63
64 # Create a Raspberry Pi object for each GPIO and set to defaults.
65
66 foreach my $gpio (sort keys %$GpioData) {
67     if ($$GpioData{$gpio}{'Obj'} == 0) {
68         if ($gpio =~ m/^GPIO(\d*)_/) {
69             $pin = $1;
70             $$GpioData{$gpio}{'Obj'} = RPi::Pin->new($pin);
71             if ($$GpioData{$gpio}{'Obj'} != 0) {
72                 &DisplayDebug(1, "Init_SignalDriver, $gpio object " .
73                     "successfully created.");
74                 $$GpioData{$gpio}{'Obj'}->mode($$GpioData{$gpio}{'Mode'});
75                 if ($$GpioData{$gpio}{'Mode'} == 0) {
76                     # 0=None, 1=Pullup, 2=Pullup
77                     $$GpioData{$gpio}{'Obj'}->pull(2); # Enable pullup on pin.
78                 }
79                 elsif ($$GpioData{$gpio}{'Mode'} == 1) {
80                     $$GpioData{$gpio}{'Obj'}->write(0); # Set GPIO low.
81                 }
82             }
83         }
84         else {
85             &DisplayError("Init_SignalDriver, failed to create " .
86                 "$gpio object. $!");
87             return 1;
88         }
89     }
90     else {
91         &DisplayError("Init_SignalDriver, failed to parse pin " .
92             "number from '$gpio'.");
93         return 1;
94     }
95 }
96
97 &DisplayWarning("Init_SignalDriver, $gpio object already active.");
98 }
99
100 # Test toggle.
101 # while (1) {
102 #     foreach my $gpio (sort keys %$GpioData) {
103 #         $$GpioData{$gpio}{'Obj'}->write(1);
104 #     }
105 #     &DisplayDebug(1, "Init_SignalDriver, All GPIOs HIGH.");
106 #     sleep 2;
107 #     foreach my $gpio (sort keys %$GpioData) {
108 #         $$GpioData{$gpio}{'Obj'}->write(0);
109 #     }
110 #     &DisplayDebug(1, "Init_SignalDriver, All GPIOs LOW.");
111 #     sleep 2;
112 # }
113 # exit(0);
114
115 # Set all signals to 'Off'. GPIO27_SCLK, GPIO22_DATA, and GPIO17_XLAT are
116 # set to 0 from above GPIO instantiation.
117
118 $$GpioData{'GPIO23_OUT'}{'Obj'}->write(1); # Blank outputs.
119 for ($x = 0; $x < $RegisterLength; $x++) {
120     $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(1); # Set SCLK high (store bit).

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121     $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(0);      # Set SCLK low.
122 }
123 $$GpioData{'GPIO17_XLAT'}{'Obj'}->write(1);          # Set XLAT high (latch data).
124 $$GpioData{'GPIO17_XLAT'}{'Obj'}->write(0);          # Set XLAT low.
125 $$GpioData{'GPIO23_OUTE'}{'Obj'}->write(0);          # Enable outputs.
126
127 &DisplayMessage("Init_SignalDriver, All signals and relays set to 'Off'.");
128 return 0;
129 }
130
131 # =====
132 # FUNCTION: SetSignalColor
133 #
134 # DESCRIPTION:
135 #   This routine sets the specified signal to the specified color. Each signal
136 #   LED is a two lead red/green device wired to the two consecutive register
137 #   bits. Red is illuminated with one current flow direction and green is
138 #   illuminated with the opposite current flow direction. Current direction is
139 #   controlled by which of the two register bits is set high/low. The local
140 #   signalColor hash holds the values for each color.
141 #
142 #   This routine is called by SetSemaphoreSignal to control lamp on/off. The
143 #   SemaphoreFlag argument is used to prevent this routine from setting the new
144 #   color value into $$SignalData{$Signal}{'Current'}. The SetSemaphoreSignal
145 #   routine will set the value once the associated servo move has completed.
146 #
147 #   The necessary mask values are created and sent to SignalChildProcess stdin
148 #   to set the specified signal (01-16) to the specified color.
149 #
150 # CALLING SYNTAX:
151 #   $result = &SetSignalColor($Signal, $Color, $SignalChildPid,
152 #                             \%SignalData, $SemaphoreFlag);
153 #
154 # ARGUMENTS:
155 #   $Signal      Signal number to set.
156 #   $Color       Signal color, 'Red', 'Grn', 'Yel', or 'Off'
157 #   $SignalChildPid PID of child signal refresh process.
158 #   $SignalData  Pointer to SignalData hash.
159 #   $SemaphoreFlag Suppresses setting of current color when set.
160 #
161 # RETURNED VALUES:
162 #   0 = Success, 1 = Error.
163 #
164 # ACCESSED GLOBAL VARIABLES:
165 #   None.
166 # =====
167 sub SetSignalColor {
168     my($Signal, $Color, $SignalChildPid, $SignalData, $SemaphoreFlag) = @_;
169     my($data1, $data2, $mask);
170
171     my(%signalColor1) = ('Off' => 0b00, 'Red' => 0b01, 'Grn' => 0b10,
172                          'Yel' => 0b01);
173     my(%signalColor2) = ('Off' => 0b00, 'Red' => 0b01, 'Grn' => 0b10,
174                          'Yel' => 0b10);
175
176     &DisplayDebug(2, "SetSignalColor, Signal: $Signal   Color: " .
177                   "$Color   SemaphoreFlag: '$SemaphoreFlag'");
178
179     if ($Signal ne "") {
180

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181 # Create mask values for the specified signal.
182 if ($Color eq 'Red' or $Color eq 'Grn' or $Color eq 'Off' or
183     $Color eq 'Yel') {
184     $mask = 0xFFFFFFFF & ~(0b11 << (($Signal - 1) * 2));
185     $data1 = $signalColor1{$Color} << (($Signal - 1) * 2);
186     $data2 = $signalColor2{$Color} << (($Signal - 1) * 2);
187
188     &DisplayDebug(2, "SetSignalColor, ----- 16151413121110 9 " .
189         "8 7 6 5 4 3 2 1");
190     &DisplayDebug(2, "SetSignalColor, mask: " .
191         sprintf("%0.32b", $mask));
192     &DisplayDebug(2, "SetSignalColor, data1: " .
193         sprintf("%0.32b", $data1));
194     &DisplayDebug(2, "SetSignalColor, data2: " .
195         sprintf("%0.32b", $data2));
196
197     Forks::Super::write_stdin($SignalChildPid, join(",", $mask, $data1,
198         $data2, "\n"));
199     $$SignalData{$Signal}{'Current'} = $Color unless ($SemaphoreFlag);
200 }
201 else {
202     &DisplayError("SetSignalColor, invalid signal color: $Color");
203     return 1;
204 }
205 }
206 else {
207     &DisplayError("SetSignalColor, invalid signal number: $Signal");
208     return 1;
209 }
210 return 0;
211 }
212
213 # =====
214 # FUNCTION: SetSemaphoreSignal
215 #
216 # DESCRIPTION:
217 #   This routine sets the specified Semaphore signal to the specified color.
218 #   SetSignalColor is called to set the lamp on (red) or off as required.
219 #   MoveTurnout is called to position the servo attached to the semaphore flag
220 #   board.
221 #
222 #   This routine is call for each iteration of the main loop until the 'Position'
223 #   value for the semaphore in SemaphoreData is set to the necessary color.
224 #
225 # CALLING SYNTAX:
226 #   $result = &SetSemaphoreSignal($Signal, $Color, $SignalChildPid, \%SignalData,
227 #       \%SemaphoreData, \%TurnoutData);
228 #
229 # ARGUMENTS:
230 #   $Signal      Signal number to set.
231 #   $Color       Signal color, 'Red', 'Grn', 'Yel', or 'Off'
232 #   $SignalChildPid PID of child signal refresh process.
233 #   $SignalData   Pointer to %SignalData hash.
234 #   $SemaphoreData Pointer to %SemaphoreData hash.
235 #   $TurnoutData  Pointer to %TurnoutData hash.
236 #
237 # RETURNED VALUES:
238 #   0 = Success, 1 = Error.
239 #
240 # ACCESSED GLOBAL VARIABLES:

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241 # None.
242 # =====
243 sub SetSemaphoreSignal {
244     my($Signal, $Color, $SignalChildPid, $SignalData, $SemaphoreData,
245         $TurnoutData) = @_;
246     my($moveResult, $servo);
247     my(%flagPosition) = ('Grn' => 'Open', 'Yel' => 'Middle', 'Red' => 'Close',
248                         'Off' => 'Open');
249
250     &DisplayDebug(1, "SetSemaphoreSignal, Signal: $Signal Color: $Color");
251
252     if ($Signal ne "" and exists($$SemaphoreData{$Signal})) {
253         $servo = $$SemaphoreData{$Signal}{'Servo'};
254         if ($$SemaphoreData{$Signal}{'InMotion'} == 1) {
255             if ($$TurnoutData{$servo}{Pid} == 0) {
256                 $$SemaphoreData{$Signal}{'InMotion'} = 0;
257                 &DisplayDebug(2, "SetSemaphoreSignal, semaphore $Signal " .
258                             "move completed.");
259
260                 # Turn on lamp unless color is off.
261                 if ($Color ne 'Off') {
262                     if (&SetSignalColor($Signal, 'Grn', $SignalChildPid, $SignalData,
263                                         'semaphore')) {
264                         &DisplayError("SetSemaphoreSignal, SetSignalColor " .
265                                     "$Signal 'Grn' returned error.");
266                         return 1;
267                     }
268                     $$SemaphoreData{$Signal}{'Lamp'} = 'On';
269                 }
270                 $$SignalData{$Signal}{'Current'} = $Color;
271                 &DisplayMessage("SetSemaphoreSignal, semaphore $Signal " .
272                             "set to $Color.");
273             }
274         }
275     else {
276         if ($$SignalData{$Signal}{'Current'} ne $Color) {
277             &DisplayDebug(1, "SetSemaphoreSignal, moving semaphore " .
278                         "$Signal to position $Color");
279
280             # Turn off lamp.
281             if (&SetSignalColor($Signal, 'Off', $SignalChildPid, $SignalData,
282                                 'semaphore')) {
283                 &DisplayError("SetSemaphoreSignal, SetSignalColor " .
284                             "$Signal 'Off' returned error.");
285                 return 1;
286             }
287             $$SemaphoreData{$Signal}{'Lamp'} = 'Off';
288
289             # Move semaphore flag board to requested position.
290             $moveResult = &MoveTurnout($flagPosition{$Color}, $servo, $TurnoutData);
291             if ($moveResult == 0) {
292                 $$SemaphoreData{$Signal}{'InMotion'} = 1;
293                 &DisplayDebug(2, "SetSemaphoreSignal, semaphore $Signal " .
294                             "$Signal move inprogress.");
295             }
296             elsif ($moveResult == 1) {
297                 &DisplayError("SetSemaphoreSignal, MoveTurnout $servo " .
298                             "$flagPosition{$Color} . " returned error.");
299                 return 1;
300             }
301         }

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301
302     # If MoveTurnout uses return 2, the servo is already in the
303     # requested position. Complete the related processing.
304     elsif ($moveResult == 2) {
305
306         # Turn on lamp unless color is off.
307         if ($Color ne 'Off') {
308             if (&SetSignalColor($Signal, 'Grn', $SignalChildPid,
309                 $SignalData, 'semaphore')) {
310                 &DisplayError("SetSemaphoreSignal, SetSignalColor " .
311                     "$Signal 'Grn' returned error.");
312                 return 1;
313             }
314             $$SemaphoreData{$Signal}{'Lamp'} = 'On';
315         }
316         $$SignalData{$Signal}{'Current'} = $Color;
317     }
318 }
319 }
320 }
321 else {
322     &DisplayError("SetSemaphoreSignal, invalid signal number: $Signal");
323     return 1;
324 }
325 return 0;
326 }
327
328 # =====
329 # FUNCTION:  SignalChildProcess
330 #
331 # DESCRIPTION:
332 #     This routine is launched as a child process during main program startup
333 #     and is used to communicate with the 74HC595 shift registers. This frees
334 #     the main code from the constant need to toggle the yellow signals between
335 #     red and green. The LEDs used in the signals should all be of similar
336 #     electrical specifications and color characterists.
337 #
338 #     Two time delays (select statements) are used to balance the red/green 'on'
339 #     time. This provides for coarse level adjustment of the yellow color for all
340 #     signals. These values should be set with the variable resistors on the shift
341 #     register board set to mid position. Then, the variable resistors are used
342 #     for fine adjustment of each signals yellow color.
343 #
344 #     The time delays further control the repetition rate of the while loop.
345 #     This rate should be just high enough to eliminate flicker when the yellow
346 #     color is displayed; about 25-30 cycles per second. The lowest possible
347 #     cycle rate is desired to minimize CPU loading by the while loop.
348 #
349 #     The while loop further optimizes itself by checking for any yellow signal
350 #     indications. Yellow signals, with opposite red/green registerBit variable
351 #     settings, will produce a non-zero result when XOR'd. When no yellow signals
352 #     are being displayed, the while loop repetition rate is reduced to 4 cycles
353 #     per second.
354 #
355 # CALLING SYNTAX:
356 #     $pid = fork { sub => \&SignalChildProcess, child_fh => "in socket",
357 #         args => [ \%GpioData ] };
358 #
359 #         $GpioData          Pointer to the %GpioData hash.
360 #

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361 # The SuperForks 'child_fh' functionality is used for communication between
362 # the parent and child processes. The parent sends new signal settings to the
363 # child's stdin. The new data is stored in the child variables and used until
364 # subsequently updated.
365 #
366 # To minimize input processing within this subroutine, the data message must
367 # be formatted as follows.
368 #
369 # <sigMask>,<sigColor1>,<sigColor2>,<terminator>
370 #
371 #     <sigMask>      - 32 bit mask, all 1's, signal position two bits set to 0.
372 #     <sigColor1>    - 32 bit mask, all 1's, signal position set to color value.
373 #     <sigColor2>    - 32 bit mask, all 1's, signal position set to color value.
374 #     <terminator>   - "-\n".
375 #
376 # SEND DATA TO CHILD:
377 #     Forks::Super::write_stdin($SignalChildPid, join(",", $sigMask, $sigColor1,
378 #                                                         $sigColor2, "-\n"));
379 #
380 # RETURNED VALUES:
381 #     PID of child process = Success, 0 = Error
382 #
383 # ACCESSED GLOBAL VARIABLES:
384 #     $main::ChildName
385 # =====
386 sub SignalChildProcess {
387     my($GpioData) = @_;
388     my($x, @buffer, $yellowSig);
389
390     # Default shift register bits.
391     my($registerBits1) = 0x00000000;
392     my($registerBits2) = 0x00000000;
393
394     $main::ChildName = 'SignalChildProcess';
395     &DisplayMessage("SignalChildProcess started.");
396
397     while (1) {
398         push(@buffer, <STDIN>);
399
400         # Check for a new complete message and process if found.
401         if ($buffer[0] =~ m/(.+?),(.+?),(.+?),-/ ) {
402             for ($x = 0; $x <= $#buffer; $x++) {
403                 print "x: $x - $buffer[$x]";
404             }
405             $registerBits1 = (($registerBits1 & $1) | $2);
406             $registerBits2 = (($registerBits2 & $1) | $3);
407             $yellowSig = $registerBits1 ^ $registerBits2;
408
409             &DisplayDebug(3, "SignalChildProcess, 1: " .
410                           sprintf("%0.32b", $1));
411             &DisplayDebug(3, "SignalChildProcess, 2: " .
412                           sprintf("%0.32b", $2));
413             &DisplayDebug(3, "SignalChildProcess, 3: " .
414                           sprintf("%0.32b", $3));
415             &DisplayDebug(1, "SignalChildProcess, registerBits1: " .
416                           sprintf("%0.32b", $registerBits1));
417             &DisplayDebug(1, "SignalChildProcess, registerBits2: " .
418                           sprintf("%0.32b", $registerBits2));
419             splice(@buffer, 0, 1); # Remove processed record.
420         }

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421
422 # Send data to 74HC595s - GPIO17_XLAT, GPIO23_OUT, GPIO27_SCLK, GPIO22_DATA
423 for my $pos (reverse(0..31)) {
424     $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(0);           # Set SCLK low.
425     $$GpioData{'GPIO22_DATA'}{'Obj'}->write(($registerBits1 >> $pos) & 0x01);
426     $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(1);           # Set SCLK high
427 }
428 $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(0);               # Set SCLK low.
429 $$GpioData{'GPIO17_XLAT'}{'Obj'}->write(1);               # Set XLAT high
430 $$GpioData{'GPIO17_XLAT'}{'Obj'}->write(0);               # Set XLAT low.
431
432 sleep 0.25 unless ($yellowSig);
433 sleep 0.006;                                               # Adjust for coarse yellow color.
434
435 for my $pos (reverse(0..31)) {
436     $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(0);           # Set SCLK low.
437     $$GpioData{'GPIO22_DATA'}{'Obj'}->write(($registerBits2 >> $pos) & 0x01);
438     $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(1);           # Set SCLK high
439 }
440 $$GpioData{'GPIO27_SCLK'}{'Obj'}->write(0);               # Set SCLK low.
441 $$GpioData{'GPIO17_XLAT'}{'Obj'}->write(1);               # Set XLAT high
442 $$GpioData{'GPIO17_XLAT'}{'Obj'}->write(0);               # Set XLAT low.
443
444 sleep 0.25 unless ($yellowSig);
445 sleep 0.019;                                               # Adjust for coarse yellow color.
446 }
447
448 &DisplayMessage("SignalChildProcess terminated.");
449 exit(0);
450 }
451
452 # =====
453 # FUNCTION: TestSignals
454 #
455 # DESCRIPTION:
456 #   This routine cycles the specified signal range between the available colors.
457 #
458 # CALLING SYNTAX:
459 #   $result = &TestSignals($Range, $SignalChildPid, \%SignalData,
460 #                           \%GradeCrossingData, \%SemaphoreData, \%TurnoutData);
461 #
462 # ARGUMENTS:
463 #   $Range           Signal number or range to use.
464 #   $SignalChildPid  PID of child signal refresh process.
465 #   $SignalData       Pointer to %SignalData hash.
466 #   $GradeCrossingData Pointer to %GradeCrossingData hash.
467 #   $SemaphoreData    Pointer to %SemaphoreData hash.
468 #   $TurnoutData      Pointer to %TurnoutData hash. (semaphore flag board)
469 #
470 # RETURNED VALUES:
471 #   0 = Success, 1 = Error.
472 #
473 # ACCESSED GLOBAL VARIABLES:
474 #   $main::MainRun
475 # =====
476 sub TestSignals {
477
478     my($Range, $SignalChildPid, $SignalData, $GradeCrossingData, $SemaphoreData,
479        $TurnoutData) = @_;
480     my($signal, $start, $end, $nmb, $color, @signalNumbers);

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481 my($cntSignal) = scalar keys %$SignalData;
482 my(@signalList) = (); my(@colorList) = ();
483 my($random, $gradecrossing) = (0,0);
484 my(%colorHash) = (1 => 'Red', 2 => 'Grn', 3 => 'Yel', 4 => 'Off');
485
486 &DisplayDebug(1, "TestSignals, Entry ... SignalChildPid: " .
487               "$SignalChildPid Range: '$Range'");
488
489 # =====
490 # Set specified color and exit.
491
492 if ($Range =~ m/^(Red):(\d+)/i or $Range =~ m/^(Grn):(\d+)/i or
493     $Range =~ m/^(Yel):(\d+)/i or $Range =~ m/^(Off):(\d+)/i) {
494     $color = ucfirst(lc $1);
495     $signal = $2;
496     if ($signal > $cntSignal or $signal <= 0) {
497         &DisplayError("TestSignals, invalid signal number: $signal");
498         return 1;
499     }
500     $signal = "0${signal}" if (length($signal) == 1);
501     if (exists ($$SemaphoreData{$signal})) {
502         &DisplayDebug(1, "TestSignals, Semaphore signal: $signal");
503         while ($$SignalData{$signal}{Current} ne $color) {
504             return 1 if (&SetSemaphoreSignal($signal, $color, $SignalChildPid,
505                 $SignalData, $SemaphoreData, $TurnoutData));
506             sleep 0.5; # Wait for servo move.
507         }
508     }
509     else {
510         return 1 if (&SetSignalColor($signal, $color, $SignalChildPid,
511             $SignalData, ''));
512     }
513     &DisplayMessage("Signal $signal set to '$color'.");
514     exit(0);
515 }
516 elseif ($Range =~ m/^(Red).*/i or $Range =~ m/^(Grn).*/i or
517         $Range =~ m/^(Yel).*/i or $Range =~ m/^(Off).*/i) {
518     $color = ucfirst(lc $1);
519     foreach my $signal (1..12) {
520         $signal = "0${signal}" if (length($signal) == 1);
521         if (exists ($$SemaphoreData{$signal})) {
522             &DisplayDebug(1, "TestSignals, Semaphore signal: $signal");
523             while ($$SignalData{$signal}{Current} ne $color) {
524                 return 1 if (&SetSemaphoreSignal($signal, $color, $SignalChildPid,
525                     $SignalData, $SemaphoreData, $TurnoutData));
526                 sleep 0.5; # Wait for servo move.
527             }
528         }
529         else {
530             return 1 if (&SetSignalColor($signal, $color, $SignalChildPid,
531                 $SignalData, ''));
532         }
533         &DisplayDebug(1, "TestSignals, Signal $signal is set to " .
534             "$$SignalData{$signal}{Current}");
535     }
536     &DisplayMessage("All signals set to '$color'.");
537     exit(0);
538 }
539
540 # =====

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541 # Process special modifiers and then setup for looped testing.
542
543 if ($Range =~ m/r.*\d/i) {
544     $random = 1;
545     $Range =~ s/r//i;
546 }
547 if ($Range =~ m/g.*\d/i) {
548     $gradecrossing = 1;
549     $Range =~ s/g//i;
550     sleep 1; # Give GcChildProcess time to start.
551 }
552
553 if ($Range =~ m/(\d+):(\d+)/) { # Range specified.
554     $start = $1;
555     $end = $2;
556     if ($start > $end or $start <= 0 or $start > $cntSignal or $end <= 0 or
557         $end > $cntSignal) {
558         &DisplayError("TestSignals, invalid signal range: '$Range' .
559             " cntSignal: $cntSignal");
560         return 1;
561     }
562     for ($signal = $start; $signal <= $end; $signal++) {
563         push (@signalList, $signal);
564     }
565 }
566 else {
567     @signalList = split(",", $Range);
568     foreach my $signal (@signalList) {
569         if ($signal !~ /\^\d+$/ or $signal > $cntSignal or $signal <= 0) {
570             &DisplayError("TestSignals, invalid signal number: $signal");
571             return 1;
572         }
573     }
574 }
575
576 &DisplayDebug(1, "TestSignals, signalList: '@signalList'");
577
578 # =====
579 # Begin looped testing..
580
581 while ($main::MainRun) {
582     # For random testing, we randomize the signalNumbers list and also the
583     # signal color. For non-random, we set each color.
584
585     if ($random == 1) {
586         &ShuffleArray(\@signalList);
587         foreach my $signal (@signalList) {
588             return 0 unless ($main::MainRun);
589             $signal = "0${signal}" if (length($signal) == 1);
590             $color = $colorHash{(int(rand(4))+1)};
591             if ($gradecrossing == 1) {
592                 if ($color eq 'Grn') {
593                     Forks::Super::write_stdin($$GradeCrossingData{'01'}{'Pid'},
594                         'start:apr');
595                 }
596                 elsif ($color eq 'Yel') {
597                     Forks::Super::write_stdin($$GradeCrossingData{'02'}{'Pid'},
598                         'start:road');
599                 }
600                 elsif ($color eq 'Off') {

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601         Forks::Super::write_stdin($$GradeCrossingData{'01'}{'Pid'},
602                                     'stop');
603     }
604     elsif ($color eq 'Red') {
605         Forks::Super::write_stdin($$GradeCrossingData{'02'}{'Pid'},
606                                     'stop');
607     }
608 }
609 &DisplayMessage("TestSignals, Signal: $signal    Color: $color");
610 if (exists ($$SemaphoreData{$signal})) {
611     &DisplayDebug(1, "TestSignals, Semaphore signal: $signal");
612     while ($$SignalData{$signal}{Current} ne $color) {
613         return 1 if (&SetSemaphoreSignal($signal, $color,
614                                     $SignalChildPid, $SignalData, $SemaphoreData,
615                                     $TurnoutData));
616         sleep 0.5;                                # Wait for servo move.
617     }
618 }
619 else {
620     return 1 if (&SetSignalColor($signal, $color, $SignalChildPid,
621                                 $SignalData, ''));
622 }
623 &DisplayDebug(1, "TestSignals, Signal $signal is set to " .
624               "$$SignalData{$signal}{Current}");
625 sleep 0.5;
626 }
627 }
628 else {
629     # Create colorList test sequence.
630     if ($#colorList < 0) {
631         foreach my $nmbr (sort keys %colorHash) {
632             push (@colorList, $colorHash{$nmbr});
633         }
634     }
635     foreach my $color (@colorList) {
636         if ($gradecrossing == 1) {
637             if ($color eq 'Grn') {
638                 Forks::Super::write_stdin($$GradeCrossingData{'01'}{'Pid'},
639                                             'start:apr');
640             }
641             elsif ($color eq 'Yel') {
642                 Forks::Super::write_stdin($$GradeCrossingData{'02'}{'Pid'},
643                                             'start:road');
644             }
645             elsif ($color eq 'Off') {
646                 Forks::Super::write_stdin($$GradeCrossingData{'01'}{'Pid'},
647                                             'stop');
648             }
649             elsif ($color eq 'Red') {
650                 Forks::Super::write_stdin($$GradeCrossingData{'02'}{'Pid'},
651                                             'stop');
652             }
653         }
654     }
655     foreach my $signal (@signalList) {
656         return 0 unless ($main::MainRun);
657         $signal = "0${signal}" if (length($signal) == 1);
658         &DisplayMessage("TestSignals, Signal: $signal    Color: $color");
659         if (exists ($$SemaphoreData{$signal})) {
660             &DisplayDebug(1, "TestSignals, Semaphore signal: $signal");
661             while ($$SignalData{$signal}{Current} ne $color) {

```

```

661         return 1 if (&SetSemaphoreSignal($signal, $color,
662             $SignalChildPid, $SignalData, $SemaphoreData,
663             $TurnoutData));
664         sleep 0.5;           # Wait for servo move.
665     }
666 }
667 else {
668     return 1 if (&SetSignalColor($signal, $color, $SignalChildPid,
669         $SignalData, ''));
670 }
671 &DisplayDebug(1, "TestSignals, Signal $signal is set" .
672     " to $$SignalData{$signal}{Current}");
673 sleep 0.75;
674 }
675 }
676 }
677 sleep 2;    # Show set signal color(s) for this time delay.
678 }
679 return 0;
680 }
681
682 return 1;
683

```